* Step 1. Use a roll command to program your Sphero with the following variables…
  + *Seconds: 6*
  + *Speed: Any speed between 0-40*
  + *Heading: 0 degrees*
* Step 2. Place your Sphero on the ground, mark your spot, and run the program.
* Step 3. Mark your end spot. Measure the distance from your robot’s start position to its end position. Record on record sheet.
* Step 1. Use a roll command to program your Sphero with the following variables…
  + *Seconds: 6*
  + *Speed: Any speed between 60-100*
  + *Heading: 0 degrees*
* Step 2. Place your Sphero on the ground, mark your spot, and run the program.
* Step 3. Mark your end spot. Measure the distance from your robot’s start position to its end position. Record on record sheet.
* Step 1. Use a roll command to program your Sphero with the following variables…
  + *Seconds: 6*
  + *Speed: Any speed between 140-180*
  + *Heading: 0 degrees*
* Step 2. Place your Sphero on the ground, mark your spot, and run the program.
* Step 3. Mark your end spot. Measure the distance from your robot’s start position to its end position. Record on record sheet.
* Step 1. Use a roll command to program your Sphero with the following variables…
  + *Seconds: 6*
  + *Speed: Any speed between 200-255*
  + *Heading: 0 degrees*
* Step 2. Place your Sphero on the ground, mark your spot, and run the program.
* Step 3. Mark your end spot. Measure the distance from your robot’s start position to its end position. Record on record sheet.